An introduction to UPPAAL

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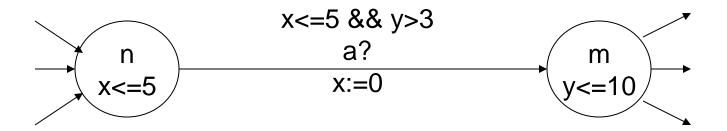
(lezione tenuta dalla prof.ssa Donatelli

UPPAAL

- Developed by the universities of Uppsala (Sweden) and Aalborg (Denmark)
 - www.uppaal.com
- Used to model check:
 - Systems expressed as networks of interacting timed automata (with discrete variables)
 - A restricted class of CTL properties (limited nesting)

Timed automata

- Recall: timed automata
 - Finite state graph equipped with a finite set of variables called clocks, which increase at the same rate as real-time



- Semantics: timed transition systems
 - E.g. of (timed) transition:

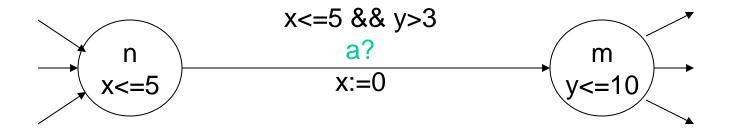
 $(n, x=2.4, y=3.1415) \rightarrow (n, x=3.5, y=4.2415)$

• E.g. of (discrete) transition:

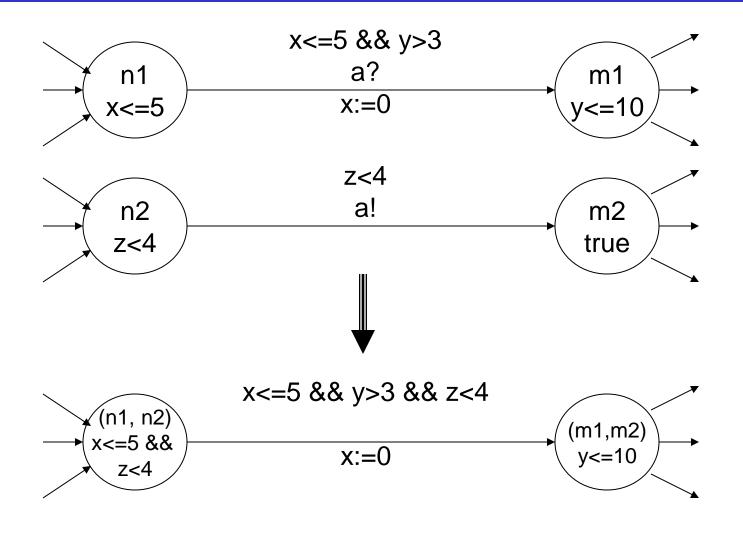
 $(n, x=2.4, y=3.1415) \rightarrow (m, x=0, y=3.1415)$

Networks of timed automata

- Model complex systems using a set of interacting timed automata
- Edges of timed automata can be labelled with actions
 - Can be used to define synchronization, as in process algebra
 - UPPAAL models feature two-way synchronization on complementary actions
 - No action label: internal action

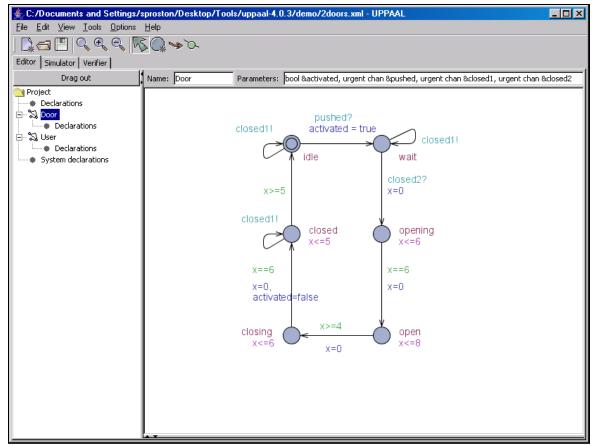


Networks of timed automata



- Other key concepts in the UPPAAL modelling language:
 - Urgency (of locations, and of synchronization channels)
 - Committed locations
 - Discrete variables (with bounded domains)
 - Constants
- There are additional concepts (more recently introduced)

System editor (to create and edit system models):



• Declaring clocks:

- Syntax:

clock x1, ..., x_n;

– Example: (to declare clocks x and y) clock x, y;

- Declaring discrete variables:
 - Syntax:

int[l,u] p1, ..., p_n;

Example: (to declare two integer variables which takes values between 0 and 255 inclusive)

int[0,255] p, q;

Example - "default" domain: (to declare an integer variable which takes values from the "default" domain [-32768, 32767])

int p;

 Example - initialisation: (to declare an integer variable which takes values between 1 and 100 inclusive, and which is initialised to 20)

int[1,100] p=20;

- Declaring channels (i.e. actions):
 - Syntax:

chan al, ..., a n;

- Example: (to declare two channels)

chan a, b;

Declaring urgent channels: (to be explained later...):
 – Syntax:

urgent chan al, ..., a n;

- Declaring boolean variables:
 - Syntax:

bool b1, ..., bn;

- Example:

bool switch=false;

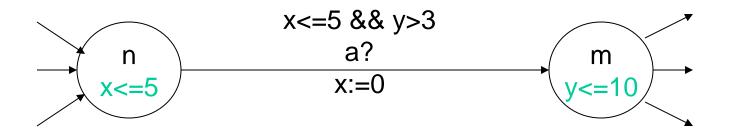
- Declaring constants:
 - Syntax:

const int c=n; const bool c=n;

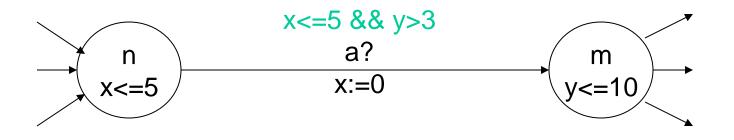
- Example:

```
const int N=1024;
```

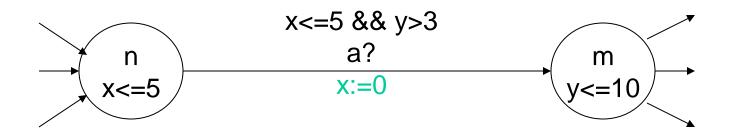
- Invariant conditions:
 - Conjunction of upper bounds on the values of clocks (the bound can be given by an expression over integers, including integer variables)
 - Example:
 - x<40 && y<=time_out*3 (where x, y are clocks, and time_out is an integer variable or integer constant)



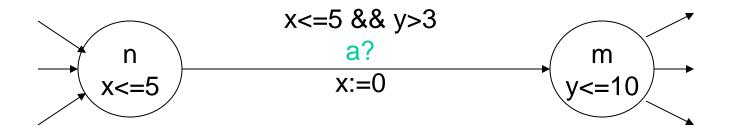
- Guards (on edges):
 - Clock guards: comparisons of values of clocks with bounds (bounds can be given as integer expressions)
 - Data guards: comparisons of values obtained by resolving integer expressions
 - For example:
 - x>backoff && backoff=bc_max (where x is a clock, backoff is an integer variable, and bc_max is an integer constant)



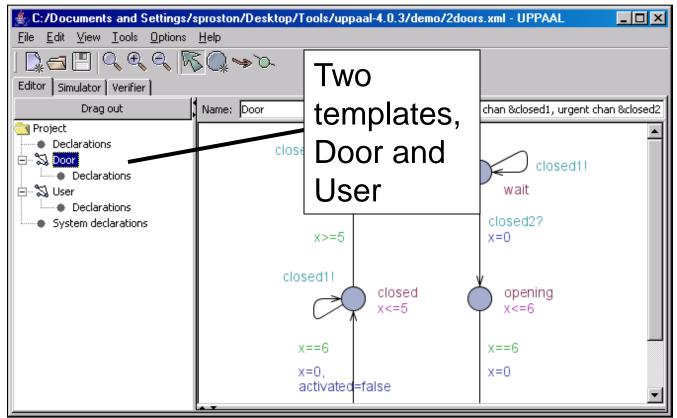
- Updates (to clocks and variables):
 - Assignment of a new value to a clock or variable (the new value may be the result of an integer expression)
 - For example:
 - x:=0 (where x is a clock)
 - x:=backoff*3 (where x is a clock and backoff is an integer variable)
 - backoff:=5 (where backoff is an integer variable)



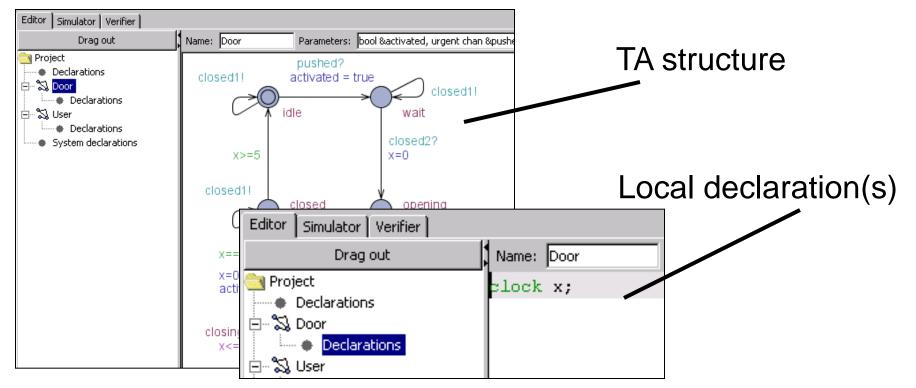
- Actions:
 - Can be of the form a!, a?, where a is the name of a channel
 - ... or the edge can be unlabelled (corresponding to choice of the edge unrestricted by other automata of the system, i.e., internal action)



- Timed automata are modelled using templates
 - The list of templates are given in the left-hand bar:



 Template: the structure of a timed automaton (represented graphically), plus a set of local declarations



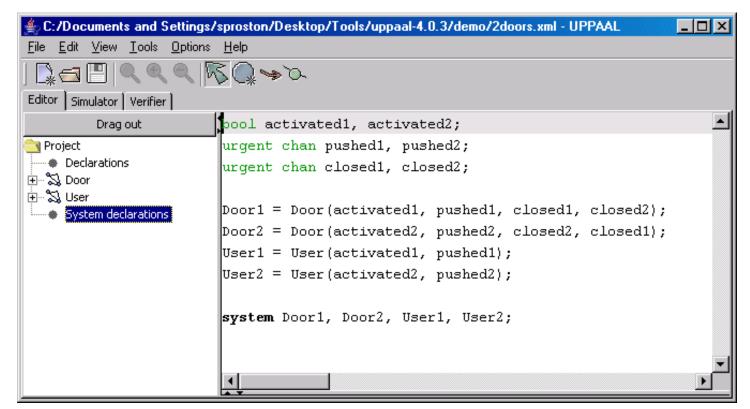
• Each template has a name and a set of parameters:

Name: Door Parameters: bool & activated, urgent chan & pushed, urgent chan & closed1, urgent chan & closed2

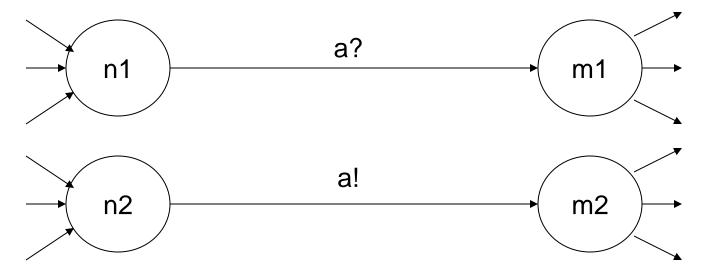
 Each template can be instantiated a number of times to obtain a number of timed automata subcomponents:

Door1 = Door(activated1, pushed1, closed1, closed2); Door2 = Door(activated2, pushed2, closed2, closed1);

 System: corresponds to a series of instantiated templates (plus global clocks, channels, data variables, constants, which may be used in the instantiated templates)



- Urgent channels
 - Suppose that in the two timed automata, the edges from n1 to m1, and n2 to m2, should be taken as soon as possible
 - That is, when both timed automata are able to synchronise on channel a
 - Solution: declare a as an urgent channel



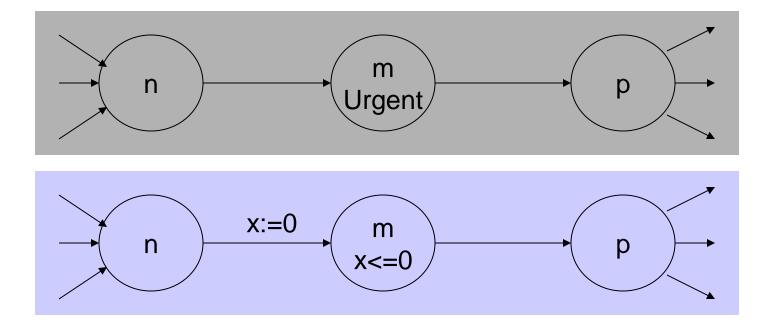
- Urgent channels
 - Recall syntax:

urgent chan al, ..., a n;

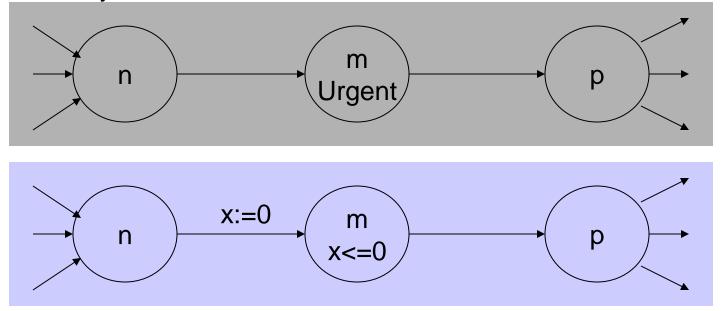
- Informal semantics: *no time delay is possible when an urgent action can be taken*
- Restrictions: it is not permitted to have clock guards on transitions with urgent channels (however, invariants and data variable guards are permitted)

- Urgent locations
 - Informal semantics: no time delay is possible when some timed automaton component of the system is in an urgent location
 - Note that this places no restriction on the (enabled) discrete transitions that can be taken when an urgent location is entered
 - E.g. TA1 enters an urgent location, then the next transition of the system can be one of TA2's enabled discrete transitions

- Urgent locations
 - What is the difference between the following two situations (from the point of view of the semantics)?



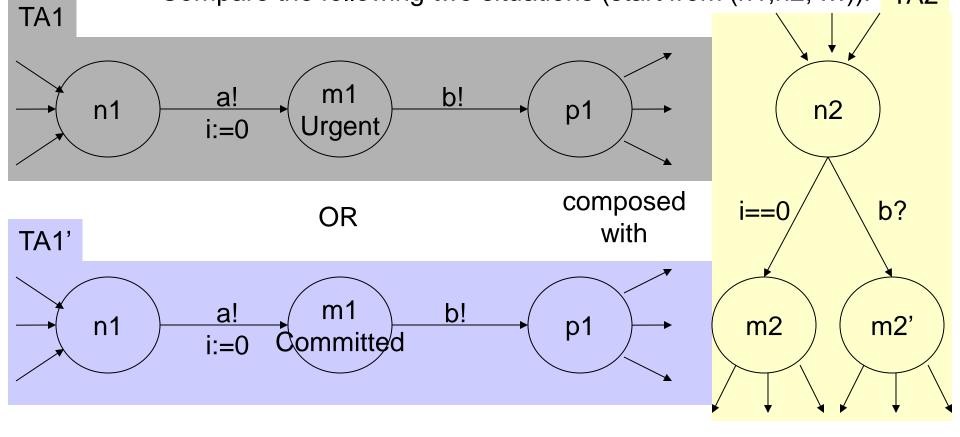
- Urgent locations
 - No difference for the semantics: it's just that we require the "extra" clock x to "simulate" urgency of location m
 - Having the extra clock is (generally) bad for modelling and analysis



- Committed locations
 - Informal semantics:
 - No time delay is possible when some timed automaton component of the system is in a committed location
 - The next transition must involve a timed automaton in a committed location

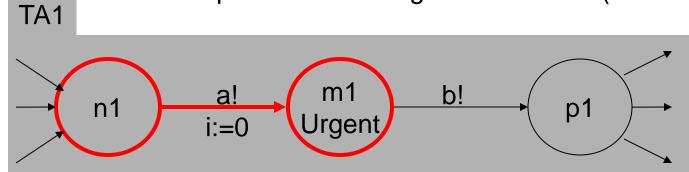
Committed locations

Compare the following two situations (start from (n1,n2, ...)): TA2

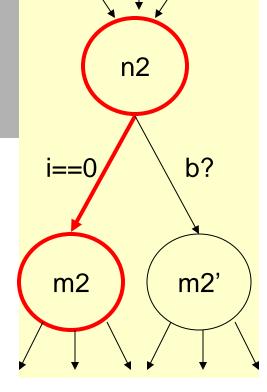


Committed locations

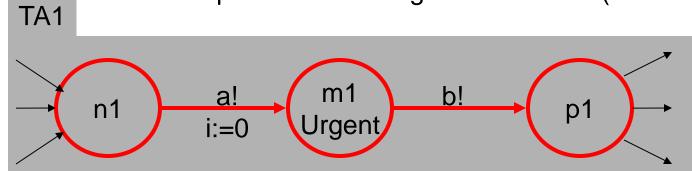




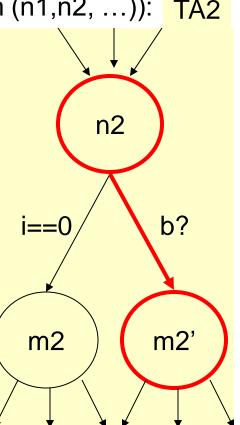
TA1 takes the first transition, then TA2 takes the left-hand transition to m2 ...



- Committed locations
 - Compare the following two situations (start from (n1,n2, ...)): TA2



... or TA1 then takes the transition to p1 and TA2 synchronises with this transition

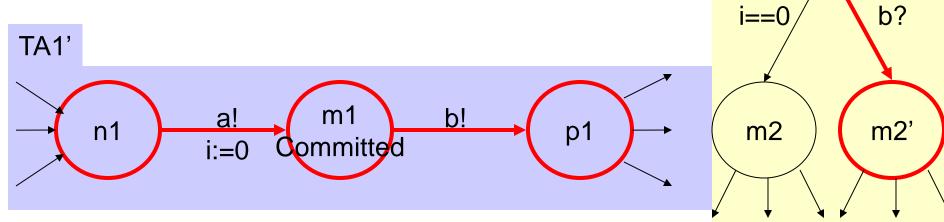


Committed locations

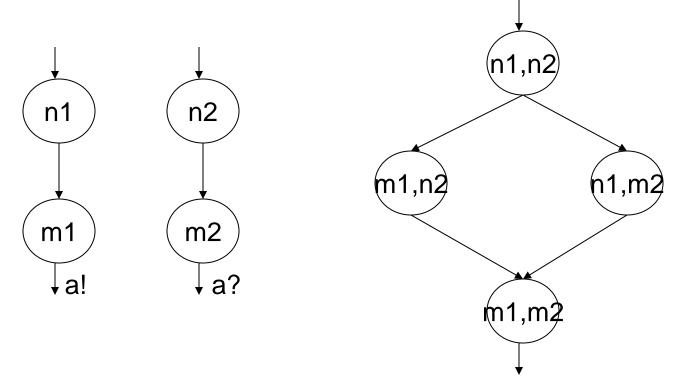
- Compare the following two situations (start from (n1,n2, ...)): TA2

n2

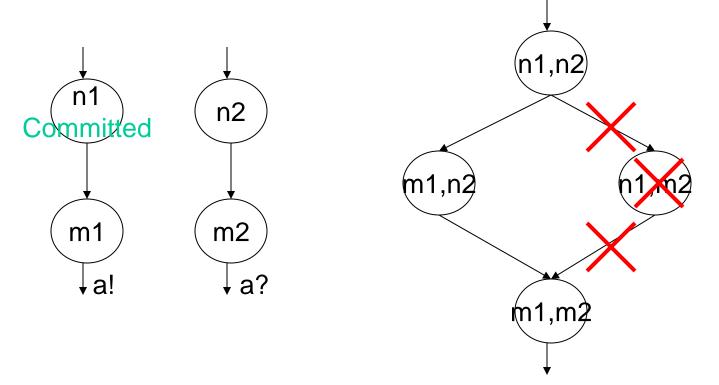
In the case the m1 is committed, TA2 does not have the opportunity to take the transition to m2: only TA1' can take a transition



- Committed locations
 - Can aid modelling (e.g. for multi-way synchronization)
 - Can reduce the interleaving in state space computation



- Committed locations
 - Can aid modelling (e.g. for multi-way synchronization)
 - Can reduce the interleaving in state space computation



- Extensions to the UPPAAL modelling language:
 - Broadcast channels
 - Arrays of data variables (which can be referred to in guards and assignments)
 - Arrays of channels, clocks and constants
 - Further operators on data variables (e.g. i++)
 - Priorities on channels and processes
 - C-like functions
 - Others ...

Verifying in UPPAAL

- Specification language: a subset of CTL
 - A[] p (corresponds to AG p)
 - A<> p (corresponds to AF p)
 - E<> p (corresponds to EF p)
 - E[] p (corresponds to EG p)
 - p --> q (corresponds to AG(p \rightarrow AF q))

Verifying in UPPAAL

• A[] p, A<> p, E<> p, E[] p, p --> q

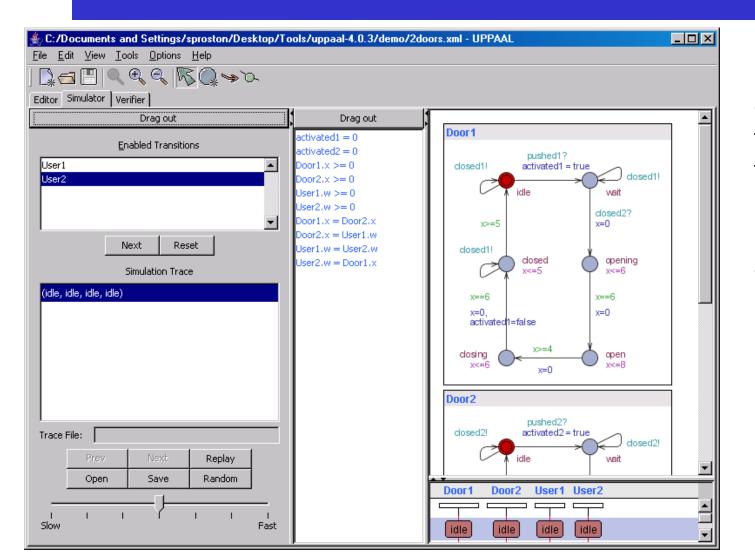
p::= a.l | gd | gc | p and p | p or p | not p | p imply p | (p)
where:

- a is the name of a timed automaton
- I is the name of a location of a
- gd is an expression over data variables
- gc is an expression over clock variables

Verifying in UPPAAL

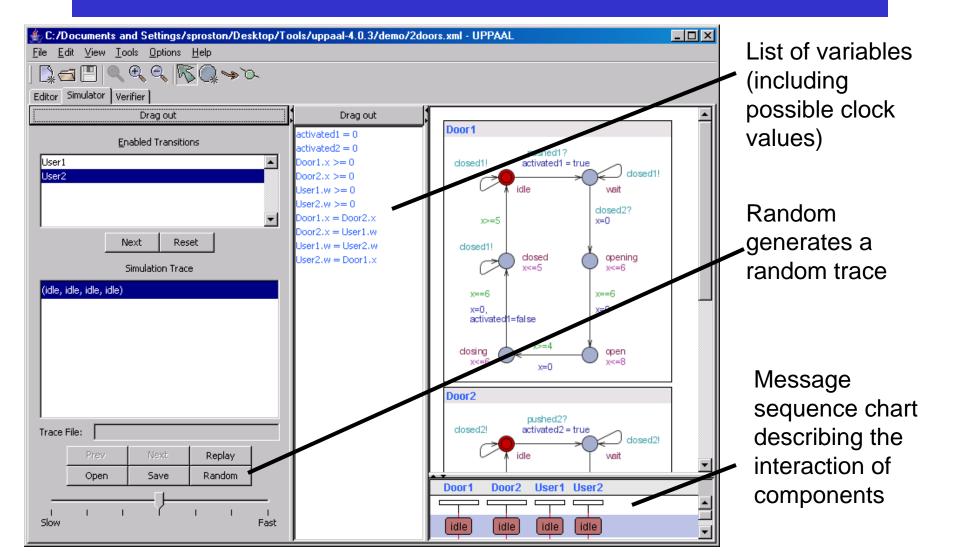
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File Edit View Tools Options Help		
$ \bigcirc \lhd \bowtie \land \land \land \bigtriangledown \land \bigtriangledown \land \land$		Check to
Editor Simulator Verifier		verify
Overview A[] not (Doorl.open and Door2.open) A[] (Doorl.opening imply Userl.w<=31) and (Door2.opening imply User2.w<=31)	Check Insert	verify a property, insert to add a
E<> Doorl.open	Remove	new property
E<> Door2.open		now property
Query		
		New queries
Comment		can be written
971204, Kim G. Larsen, Fredrik Larsson, Paul Pettersson & Arne Skou, at Fairmont Hotel, San Francisco, USA. 871209, Baul, finalized, in the air between San Francisco and London	× •	here
Status		
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UPPAAL's simulator



Permits exploration of the system following a (random or userspecified) behaviour

UPPAAL's simulator



UPPAAL's simulator

- The simulator can be used to visualise "error traces" generated by the verifier (choosing an option from "Diagnostic trace")
- For example:
 - If E<> p is satisfied, UPPAAL can return a trace which leads from the initial state to a state in which p is true
 - Dually, if A[] p is not satisfied, UPPAAL can return a trace which leads from the initial state to a state in which p is false
 - Similar for E [] p and A<> p, except traces containing loops are returned