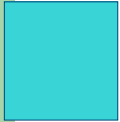


## Vector model

- Images:
  - color histogram, shape, edges, etc.



2D Matrix

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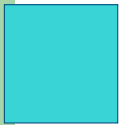
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## Vector model

- Images:
  - color histogram, shape, edges, etc.



2D Matrix



1D feature vector

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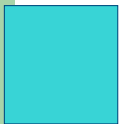
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## Vector model

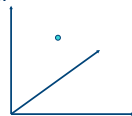
- Images:
  - color histogram, shape, edges, etc.



2D Matrix



1D feature vector



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## Vector model

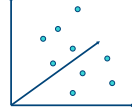
- Images:
  - color histogram, shape, edges, etc.



2D Matrix



1D feature vector



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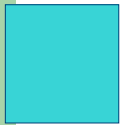
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## Vector model

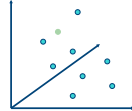
- Images:
  - color histogram, shape, edges, etc.



2D Matrix



1D feature vector



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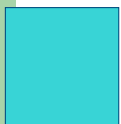
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## Vector model

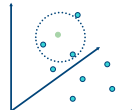
- Images:
  - color histogram, shape, edges, etc.



2D Matrix



1D feature vector



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## Vector model

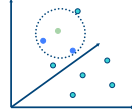
- Images:
  - color histogram, shape, edges, etc.



2D Matrix



1D feature vector



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## Vectors...what are they???

- Image with 1 pixel  $\langle 5 \rangle$



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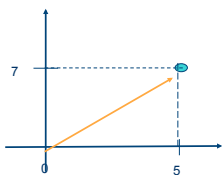
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## Vectors...what are they???

- Image with 2 pixels  $\langle 5, 7 \rangle$



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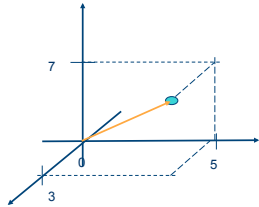
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## Vectors...what are they???

- Image with 3 pixels  $\langle 5,7,3 \rangle$



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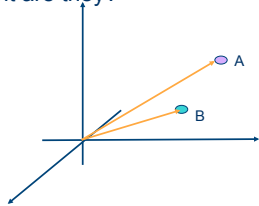
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## Distance between two images???

- Given  $A \langle a_1, a_2, a_3 \rangle$  and  $B \langle b_1, b_2, b_3 \rangle$ , how different are they?



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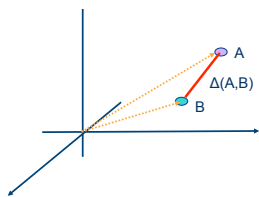
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## Euclidean distance

$$\Delta(A,B) = \sqrt{(a_1 - b_1)^2 + (a_2 - b_2)^2 + (a_3 - b_3)^2}$$



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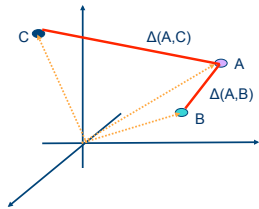
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Which image is more similar to A?



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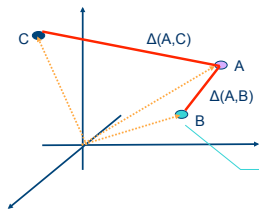
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Which image is more similar to A?



Closer to A  
Similar to A

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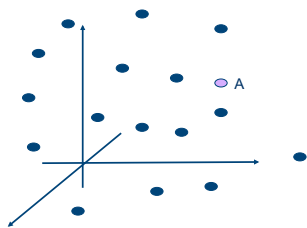
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“Find 2 most similar images to A”



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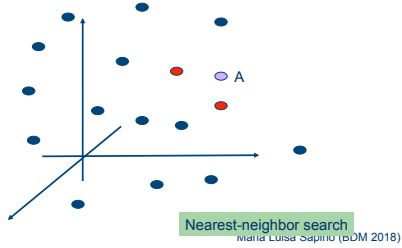
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### “Find 2 most similar images to A”



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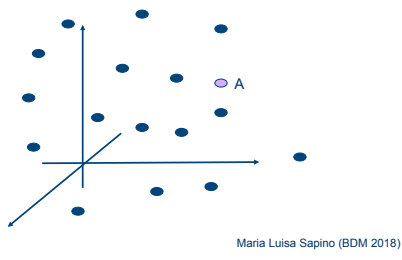
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### “Find images at most $\delta$ different from A”



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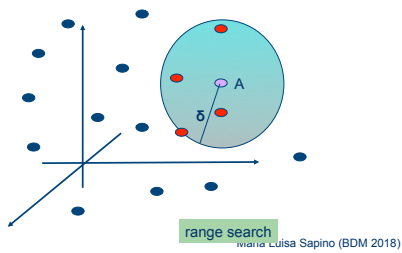
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### “Find images at most $\delta$ different from A”



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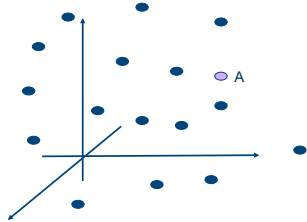
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## Are there other similarity measures?



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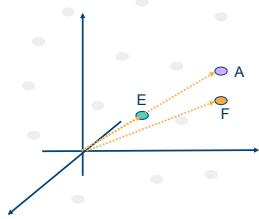
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## Let's try angles...



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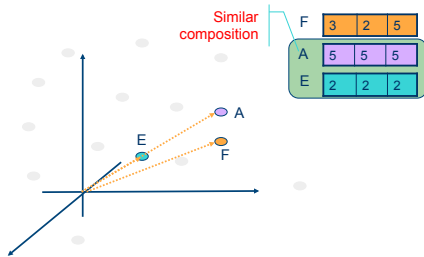
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## Let's try angles...



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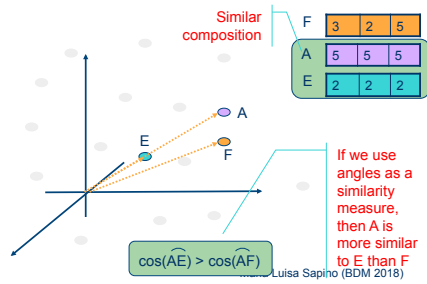
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## Let's try angles...




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## Angle-based measures

- Given

$$\vec{x} = \langle x_1, x_2, \dots, x_n \rangle \quad \vec{y} = \langle y_1, y_2, \dots, y_n \rangle$$

- Dot product

$$\vec{x} \cdot \vec{y} = \sum_{i=1}^n x_i y_i$$

- Cosine similarity

$$\cos(\vec{x}, \vec{y}) = \frac{\vec{x} \cdot \vec{y}}{|\vec{x}| |\vec{y}|}$$

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## What is a good measure then??

- Application dependent...
- ...but, distances in a metric space help indexing!

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## Metric model: axioms

- Any function  $d$  expressing a distance must satisfy the following axioms:

- self-minimality:  $d(s,s) = 0$
- minimality  $d(s_1, s_2) \geq d(s_1, s_1)$
- symmetry  $d(s_1, s_2) = d(s_2, s_1)$
- triangular inequality  $d(s_1, s_2) + d(s_2, s_3) \geq d(s_1, s_3)$

- Example: Euclidean distance

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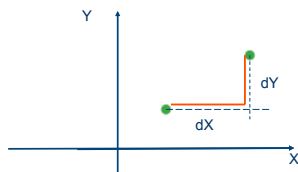
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## Metric distances (Minkowski metrics)

- L1-metric:  $d = (dX+dY)$



Also called Manhattan Distance

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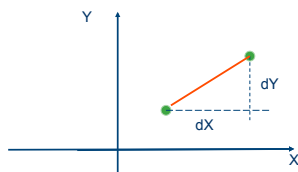
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## Metric distances (Minkowski metrics)

- L2-metric:  $d = (dX^2+dY^2)^{1/2}$



Also called Euclidean Distance

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## Metric distances (Minkowski metrics)

- L3-metric;  $d = (dX^3 + dY^3)^{1/3}$
- .....
- .....
- L(infinity);  $d = \max\{X, Y\}$

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## ...metric model

- Well suited for certain kinds of similarity evaluation, such as color based comparisons
- Consistent with widely used approaches from computer vision and pattern recognition communities
  - results suggest that the L1 metric may better capture human notions of image similarity.
- Makes it relatively easy to index data, modeled as vectors of properties, in terms of classical multi-dimensional indexing techniques.

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